

Original research paper
UDC 621.382.33:621.314.57
DOI 10.7251/IJECC1701046J
COBISS.RS-ID 7196952

Efficient Control of *IGBT* Transistor as Part of Overvoltage Protection

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Abstract - The paper analyzes the phenomena of appearance of overvoltage during the switching-off of the *IGBT* transistor which are caused by the presence of parasitic inductance in the switching circuit. This problem can be solved in two ways – by preventing the cause of the overvoltage, or by limiting the overvoltage level. Therefore, the characteristics of good PCB design have been noted, and the typical snubber's circuits have been listed. The paper focuses on solving the problem of *IGBT* transistor overvoltages on a specific power electronics converter. A computerized model of power electronics converter has been created in order to analyze the influence of parasitic inductance on the overvoltage level. A special analysis was performed on the simulation results which indicate that the control of the *IGBT* transistor turning-off process can provide a lower overvoltage level. The paper also describes the design and the implementation of the overvoltage protection elements on a developed power electronics converter prototype. The driver circuit *TD350* which performs intelligent control of *IGBT* transistors in order to control overvoltages has been described in detail. The efficiency of this driver is based on the idea of two-level turn-off, where the intermediate level and its duration can be set according to the specific conditions in the *IGBT* transistor circuit. This way, the speed of current change is reduced, which directly affects the overvoltage level on the transistor switching. Finally, within experimental results, the waveforms of control signals, as well as the overvoltage waveforms have been shown at different input voltage levels.

Keywords - component; parasitic inductance; overvoltage protection; power converter; *IGBT*.

I. INTRODUCTION

Nowadays, it is difficult to imagine an electronic device without any power electronic converters. Each converter contains at least one switching element (electronic switch) which has a key role in its operation. This means that the reliability and efficiency of the electronic device is directly dependent on the reliable and efficient operation of the switching element.

When selecting the switch, it is important to make sure that its characteristics such as nominal current and voltage satisfy the current and voltage characteristics of its environment. In addition to the nominal value of the electrical element parameters, each of them always includes, to a lesser or greater extent, the parasitic components from other elements. Their presence usually negatively affects the operation of the system.

This paper will discuss the influence of parasitic components on the appearance of overvoltage on switching elements, which

can seriously influence their reliability and operational efficiency. The major methods for the overvoltage suppression will be listed. Finally, a specific method of overvoltage protection of *IGBT* transistors based on the *TD350* control circuit will be presented.

II. PARASITIC INDUCTANCE AND ITS INFLUENCE ON OVERVOLTAGE ON SWITCHING ELEMENTS

In schematic diagram, the connections between electronic components are represented as ideal conductors – without any resistance, inductance or capacitance. However, this is frequently not the case in practice, because the connections are normally made of materials with finite conductance (such as copper, aluminum, platinum, silver, gold...). Also, their surface, shape and mutual positioning determines the size of inductance and/or capacitance between them. Since these values are usually very low and their influence is usually negative, they are frequently called “parasitic”. For example, the parasitic inductance of copper on the PCB layer with 70 μm thickness, 35 mm length and 10 mm width, is around 20 nH [1].

During the turn-off period, the energy accumulated in parasitic inductances (L_p), through which a current is flowing, that the switch needs to interrupt, will be released, which leads to the appearance of an overvoltage over the switch. The

This paper is a revised and expanded version of the paper presented at the XVI International Symposium INFOTEH-JAHORINA 2017 [9].

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overvoltage magnitude is directly proportional to the amount of accumulated energy in the parasitic inductance and the turn-off time (1).

$$V(t) = L_p \cdot di/dt \quad (1)$$

The overvoltage formed in this manner has sufficient energy to permanently damage the switch and / or generate electromagnetic interference, which makes it very important to limit or completely eliminate their occurrences while designing the converter.

III. THE METHODS FOR PREVENTING AND LIMITING THE OVERVOLTAGE IN POWER CONVERTERS

While designing the overvoltage protection, one needs to be aware of the overvoltage causes, whose function is mentioned in the previous paragraph with equation (1). This paper will demonstrate how the reduction of parasitic components (primarily inductance) and intelligent control of the switch operation can reduce the overvoltage which formed during turn-off period.

The reduction of parasitic components is accomplished by properly designing the connections between the converter elements – PCB layout design. This means that the connections should be as short as possible. Also, the surface of the loop formed by reactive and switching elements should be as small as possible.

While selecting the method for the switching control, care must be taken. Reducing the switching speed will reduce the overvoltage. However, this will also increase the switch loss, due to increase of transition time between ON and OFF state (turn-off period). Additional losses require additional cooling, which makes the design more costly [2, 3].

There are many designs available in the market which provide intelligent control algorithms and which keep the overvoltage and switch losses within the desired boundaries. One such design was used for this paper, which will be additionally discussed.

In addition to the methods for preventing the cause of their appearance, there are additional methods for reducing the existing overvoltage, where some of the switching losses energy is dissipated on snubbers or returned towards the energy source. There have been many attempts to derive universal classification scheme for snubbers. The problem is the many different function performed by circuits which are called “snubbers”. In general, such schemes haven’t been particularly useful but for the purposes of this article, snubbers will be grouped with similar characteristics. None of these distinctions are very rigorous, but are convenient to subdivide the discussion [4].

A. Passive overvoltage protection

Passive overvoltage protection consists of mostly linear elements (resistors, capacitors and/or inductors). The switching loss energy is dissipated on snubbers (Fig. 1).

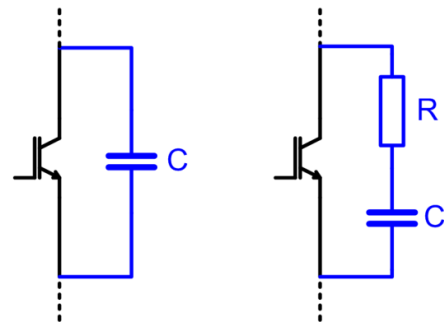


Figure 1. An examples of passive types of snubbers

B. Active overvoltage protection – with energy dissipation

This type of protection consists of active elements, such as diodes (or electronic switches in general), combined with resistors, inductors and/or capacitors. The switching loss energy is dissipated on the overvoltage protection or returned in the switch control circuit, which leads to turning the switch on again, which prevents the further increase of overvoltage amplitude (Fig. 2).

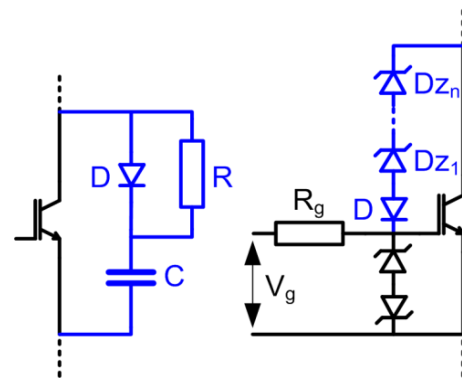


Figure 2. An examples of active snubbers with energy dissipation

C. Active overvoltage protection – with energy recuperation

Active overvoltage protection with energy recuperation redirects the switching loss energy towards the energy source through a voltage adaptation circuit, instead of dissipating it on snubbers (Fig. 3).

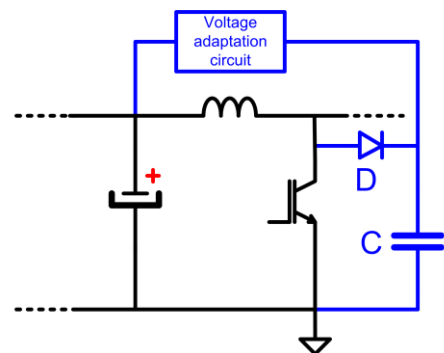


Figure 3. An example of active overvoltage protection with energy recuperation

IV. AN EXAMPLE OF REALIZATION OF EFFICIENT OVERVOLTAGE PROTECTION OF IGBT TRANSISTORS

Due to their robustness (capability of withstand high current and voltage stress) and ease of control, IGBT transistors are frequently used as switches in power converters with high rated power (tens or even hundreds of kilowatts). An efficient method of protecting IGBT transistors from overvoltage effects, based on a combination of passive and active types of overvoltage protection and intelligent control, will be demonstrated on an example of a power converter, which will be described in detail.

A. The Power Converter Structure and IGBT Transistor Operating Conditions

The power converter which is the subject of this paper represents the central part of the electronic load system used to simulate a purely resistive programmable load. Its basic structure is very simple (Fig. 4).

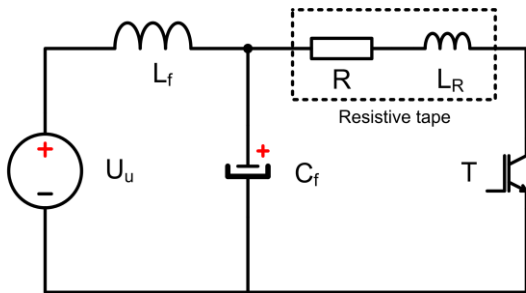


Figure 4. Schematic of electronic load

A filter at the input, consisting of L_f inductance and C_f capacitor, provides continuous current from the source U_u . The element which dissipates most of the power is a resistive tape placed in a spiral. As such, in addition to its resistance R , the tape also has inductance – parasitic inductance L_R . The current

regulation is performed using an IGBT transistor T , which operates in a switching mode. The entire electronic load system is designed to operate with voltage of up to 500 VDC and maximum power of up to 25 kW.

B. The Computer Model of the Converter

Due to the need to analyze the influence of parasitic inductances of connections between the transistor and associated converter elements on the appearance of overvoltage, a computer model has been created (Fig. 5) with real models of individual elements of the converter (which include parasitic values of resistance, capacitance and inductance). The parameters of the individual elements are modeled based on the manufacturer's catalog data. Furthermore, the parasitic inductances of the resistive tape (L_R) as well as parasitic inductances (L_V) and resistances (R_V) of copper on the PCB lines were measured using a RLC meter SANWA-LRC700.

The results of the simulation provide answers to two different questions: how do the parasitic inductances of the PCB lines affect the distribution of overvoltage between specific points on the converter, and the influence of turn-off process control on the overvoltage level. The results which will be presented and analyzed were obtained with the following simulation parameters: $U_{in}=480$ VDC, $I_{in}=60$ A, $f_{sw}=20$ kHz, gate turn-on and turn-off voltage $U_{g1}=15$ VDC i $U_{g2}=-9$ VDC, respectively. Considering the approximation (2), which describe dependence between turn-off time T_f and turn-off gate current I_{goff} , where the parameter Q_g represent the total gate charge (listed by the transistor manufacturer), the change of turn-off time T_f has been simulated using the change of turn-off gate current I_{goff} .

$$T_f \approx Q_g / I_{goff} \quad (2)$$

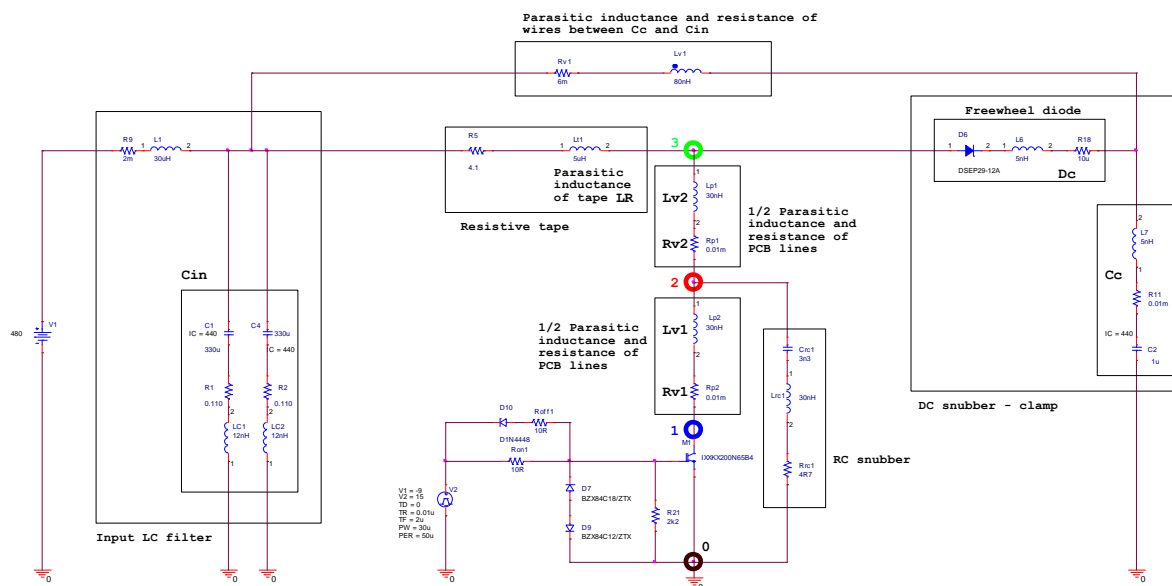


Figure 5. Computer model of the power converter (created in OrCAD)

1) Influence of parasitic inductance of PCB lines on the distribution of overvoltage. The connection of the collector of IGBT transistor with the DC diode consists of two parts in the models – the part between collector (point 1 in Fig. 5) and the resistor R_{RC1} (point 2 in Fig. 5) has been modeled using a resistance ($R_{V1}=10\ \mu\Omega$) and parasitic inductance ($L_{V1}=30\ \text{nH}$). Furthermore, the part between point 2 and the anode of the DC diode (point 3 in Fig. 5) has also been modeled using a resistance ($R_{V2}=10\ \mu\Omega$) and parasitic inductance ($L_{V2}=30\ \text{nH}$).

The Fig. 6 shows the voltage waveforms in points 1, 2 and 3, in case of transistor turn-off time of $T_f=100\ \text{ns}$. It is easy to notice that the overvoltage has the highest value on the collector of IGBT transistor (points 1). This shows that the overvoltage level, for same turn-off time, is directly related to the magnitude of the parasitic inductance which exists in the lines between switching element and the other elements of the power converter.

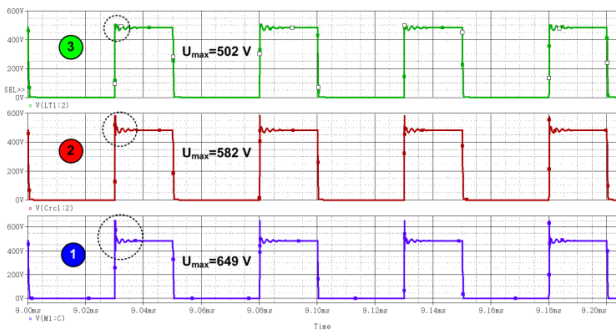


Figure 6. Influence of parasitic inductances on the overvoltage distribution ($T_f=100\ \text{ns}$)

2) The influence of transistor turn-off process control on the overvoltage level. The Fig. 7 shows the voltage waveforms in the three characteristic points (1, 2 and 3) under the same conditions as in the previous test, with the transistor turn-off time increased from 100 ns to 2 μs . In the point 3, the overvoltage level is effectively unchanged. However, the overvoltage in other points has been significantly reduced. In the point 2 the overvoltage has been reduced by 38 V (6,5%), while in the point 1 the overvoltage has been reduced by as much as 57 V (8,7%).

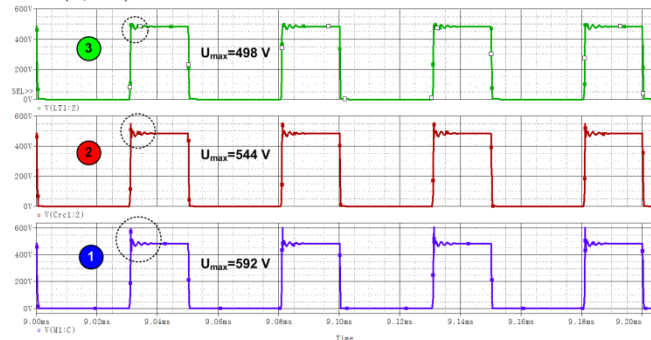


Figure 7. The influence of the transistor turn-off time on the overvoltage level ($T_f=2\ \mu\text{s}$)

Since the overvoltage level depends on the rate of change of transistor current (equation (1)) and based on the obtained

simulation results, it is possible to conclude that controlling of the turn-off process of the transistor can influence the level of overvoltage in the moment of switching it off.

Considering the fact that the transistor parasitic capacitance between the gate and the emitter C_{GE} and between the gate and the collector C_{GC} (Miller's capacitance), which determine the Q_g parameter, are non-linear, in other words that they depend on the circuit conditions, specifically the collector-emitter (V_{CE}) and gate-emitter (V_{GE}) voltage, the detail mathematical relations between T_f and overvoltage level ΔU_{CE} is a complex subject and has not been covered in detail in this paper. More details can be found in literature [5] and [6].

Due to the non-linearity of the function $\Delta U_{CE} = f(T_f)$, which is the consequence of existence of parasitic capacitance C_{GE} and C_{GC} and the phenomena of their charging/discharging, an intelligent control method is required in order to control level of ΔU_{CE} effectively [7].

For the purpose of driving the IGBT transistor of the developed converter that is the subject of this paper, a TD350 driver has been used, which will be discussed in more detail below.

C. Realisation of intelligent driving of IGBT – integrated circuit TD350.

The TD350 device is an advanced gate driver for IGBTs and power MOSFETs. Control and protection functions are included and allow the design of high reliability systems. The innovative active Miller clamp function eliminates the need for negative gate drive in most applications and allows the use of a simple bootstrap supply for the high side driver (Fig. 8).

The device includes a two-level turn-off feature with adjustable level and delay. This function protects against excessive overvoltage at turn-off in case of overcurrent or short-circuit conditions. The same delay set in the two-level turn-off feature is applied at turn-on to prevent pulse width distortion. The device also includes IGBT desaturation protection and a FAULT status output, and is compatible with both pulse transformer and optocoupler signals. [8]

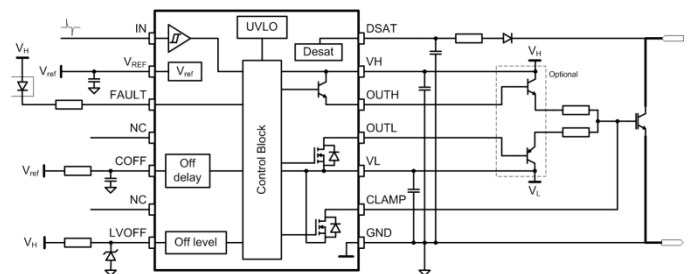


Figure 8. Functional block diagram [8]

The input (IN) is compatible with optocouplers or pulse transformers. The input is triggered by the signal edge and allows the use of a small-sized, low cost pulse transformer. Input is active low (output is high when input is low) to ease the use of the optocoupler. When driven by a pulse transformer, the input pulse (positive and negative) width must be larger than the minimum pulse width t_{onmin} .

Desaturation protection (DSAT) ensures the protection of the *IGBT* in the event of overcurrent. When the DESAT voltage goes higher than 7 V, the output is driven low (with 2-level turn-off, if applicable). The FAULT output is activated. The FAULT state is exited at the next falling edge of IN input. A programmable blanking time is used to allow enough time for *IGBT* saturation.

A **Miller clamp** allows the control of the Miller current during a high dV/dt situation and can eliminate the need for a negative supply voltage. During turn-off, the gate voltage is monitored and the clamp output is activated when gate voltage goes below 2 V (relative to GND). The clamp voltage is V_L+3 V max. for a Miller current up to 500 mA. The clamp is disabled when the IN input is triggered again.

The two-level turn-off (TLTF) is used to increase the reliability of the application. In the event of a short-circuit or over-current in the load, a large voltage overshoot can occur across the *IGBT* at turn-off and can exceed the *IGBT* breakdown voltage. By reducing the gate voltage before turn-off, the *IGBT* current is limited and the potential over-voltage is reduced. This technique is called a two-level turn-off (TLTF). Both the level and duration of the intermediate off-level are adjustable. Duration is set by an external resistor/capacitor in conjunction with the integrated voltage reference for accurate timing. The level can be easily set by an external Zener diode, and its value is selected depending on the *IGBT* characteristics. This TLTF sequence takes place at each cycle; it has no effect if the current does not exceed the normal maximum-rated value, but protects the *IGBT* in case of over-current (with a slight increase of conduction losses) [8].

This principle is shown in Fig. 9. During the TLTF time, the OUTL output is controlled by a comparator between the actual OUTL pin and an external reference voltage. When the voltage on OUTL goes down as a result of the turn-off and reach the reference threshold, then the OUTL output is disabled and the *IGBT* gate is not discharged further. After the TLTF delay, the OUTL output is enabled again to end the turn-off sequence.

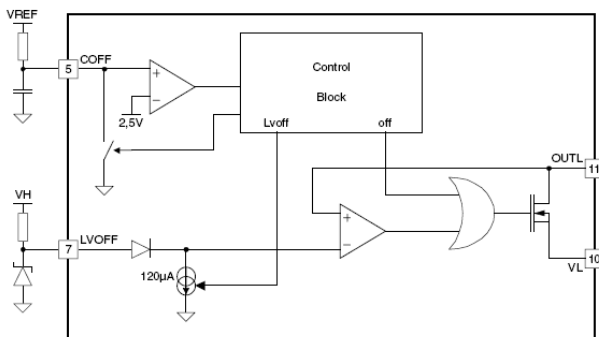


Figure 9. Principle schematic for two-level turn-off feature

The duration of the TLTF is set by the external RC components, and is given by (3):

$$T_a[\mu s] \approx 0.7 \cdot R_{off}[k\Omega] \cdot C_{off}[nF] \quad (3)$$

To keep the output signal width unchanged relative to the input signal, the turn-on is delayed by the same value as the TLTF delay.

Minimum ON time. In order to ensure the proper operation of the 2-level turn-off function, the input ON time (T_{win}) must be greater than the T_{winmin} value (4):

$$T_{winmin}[\mu s] = T_a[\mu s] + 2 \cdot R_{del}[k\Omega] \cdot C_{off}[nF] \quad (4)$$

R_{del} is the internal discharge resistor and C_{off} is the external timing capacitor. Input signals smaller than T_a are ignored. Input signals larger than T_{winmin} are transmitted to the output stage after the T_a delay with minimum width distortion (5).

$$(\Delta T_w = T_{wout} - T_{win}) \quad (5)$$

For an input signal width T_{win} between T_a and T_{winmin} , the output width T_{wout} is reduced below T_{win} (pulse distortion) and the *IGBT* could be partially turned on. These input signals should be avoided during normal operation.

The output stage is able to sink 2.3 A and source 1.5 A (typ.) at 25 °C (1.2 A/0.75 A minimum over the full temperature range). Separate sink and source outputs allow independent gate charge and discharge control without an extra external diode.

Undervoltage detection protects the application in the event of a low V_H supply voltage (during startup or a fault situation). During undervoltage, the OUTH pin is open and the OUTL pin is driven low. Fault output signals the undervoltage state and is reset only when undervoltage state disappears.

D. Results Obtained on the Developed Converter Prototype

Based on the knowledge obtained from theory of causes and effects of overvoltage in power converters, as well as the analysis of the simulated model results, a converter prototype has been developed whose diagram, with the elements of overvoltage protection, is shown in Fig. 10.

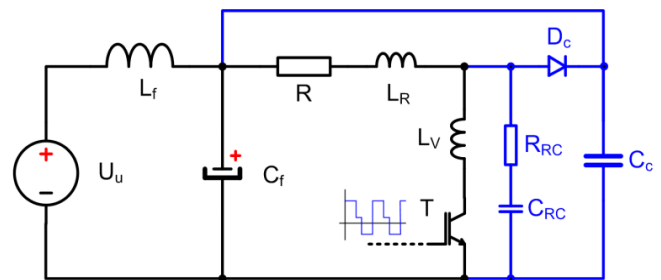


Figure 10. Schematic diagram of developed converter prototype with the elements of overvoltage protection

Due to the parasitic inductance of the resistive tape ($L_R \approx 5 \mu H$), an overvoltage protection of *IGBT* transistor has been formed as a combination of active (D_C-C_C) and passive ($R_{RC}-C_{RC}$) overvoltage protection. Due to presence of parasitic inductances ($L_V \approx 60$ nH) of connections between the *IGBT* transistor and its surroundings and strict requirement for overvoltage level, additional measures were necessary to reduce overvoltage to an acceptable level – specifically, intelligent transistor driving.

The driving of *IGBT* transistor was performed by the *TD350* control circuit. The TLTF function is configured in the following manner: turn-on voltage level $V_H=15$ VDC, turn-off voltage level $V_L=-9$ VDC, turn-off delay time $T_a=2$ μ s and the intermediate off-level $LV_{OFF}=2.5$ V. The full waveform of realized driving signal of the *IGBT* transistor has been shown in Fig. 11.

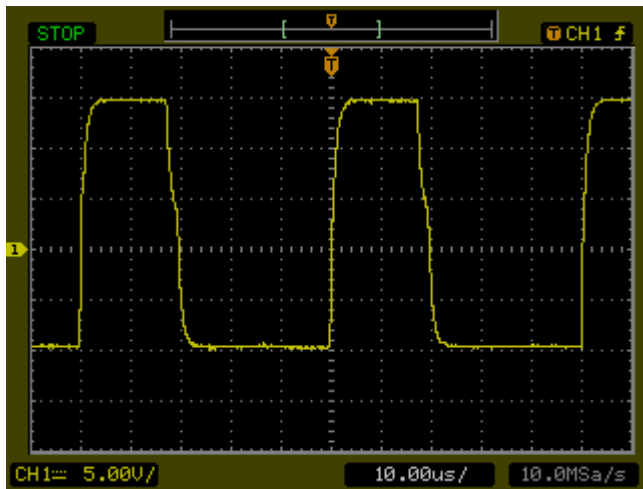


Figure 11. Achieved TLTF control signal waveform

The Fig. 12 shows a part of the PCB of the developed converter prototype. The marked sections show the positions of the *IGBT* transistor and the overvoltage protection elements.

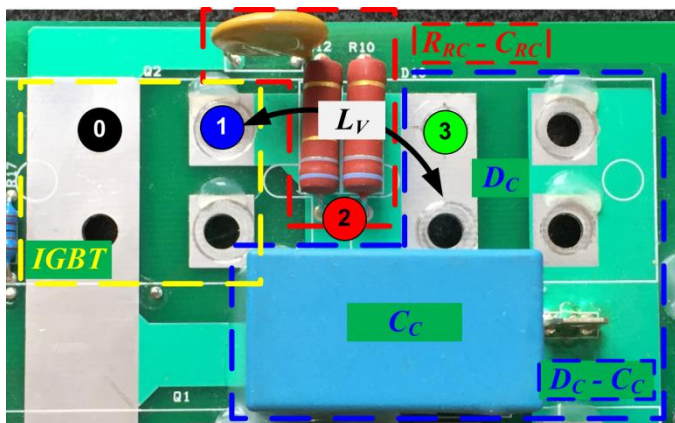


Figure 12. Developed converter prototype – the positions of the *IGBT* transistor and the overvoltage protection

As seen in the Fig. 12, the elements have been positioned in such a way to reduce the connection lines length to a minimum. This also reduces the parasitic inductances of these connections. Also, the marked points 1, 2 and 3 are the voltage measurement points discussed during the simulation results analysis (Fig. 6 and Fig. 7). The next section will provide an overview and result analysis from the developed converter prototype.

In the *IGBT* transistor voltage waveform (U_{CE}) at $U_{in}=480$ VDC and $I_{in}=60$ A, shown in Fig. 13, it is possible to see that the overvoltage, shown as a thin “spike” is practically gone. The only visible part is the muffled sinewave oscillation whose

frequency matches the resonant frequency of the passive part of overvoltage protection – RC snubber.

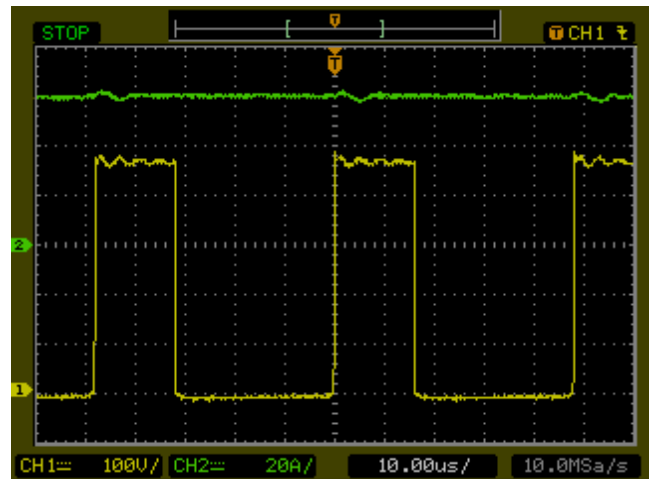


Figure 13. Waveform U_{CE} (CH1) and I_{in} (CH2) at $U_{in}=480$ VDC

For the sake of comparison, Fig. 14 shows the voltage waveform U_{CE} with the turn-off time $T_{fA}=100$ ns (without TLTF) and $T_{fB}=2$ μ s (with TLTF). In both cases, the values of input voltage and current were $U_{in}=300$ VDC and $I_{in}=70$ A.

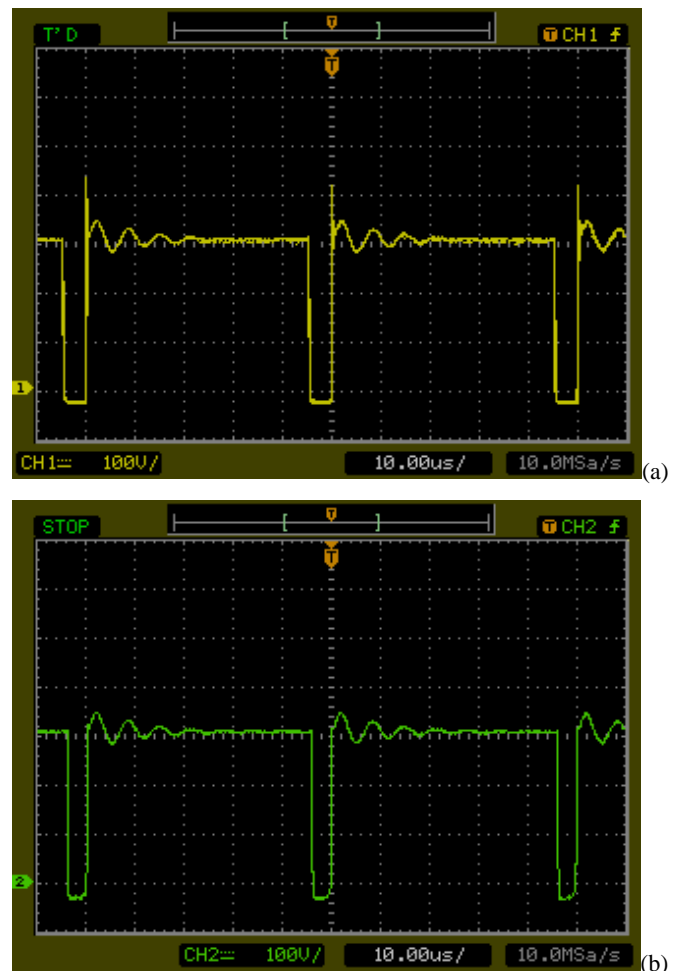


Figure 14. Voltage waveforms U_{CE} without TLTF (a) and with TLTF (b)

There is an obvious difference between the overvoltage levels for these two cases. Without TLTF and for $T_{fA}=100$ ns, the maximum value of the U_{CE} voltage is 440 V, while with TLTF and for $T_{fB}=2$ us, the maximum voltage value is significantly lower and amounts to 350 V.

The demonstrated experimental results are a clear indicator that the switching elements in power converters can be provided with operating conditions which guarantee reliability and efficiency in both normal and fault conditions with a proper design of overvoltage protection. This implies that during designing process, attention should be paid to the:

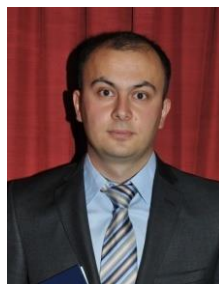
- minimization of parasitic elements of converters (PCB layout design),
- design of overvoltage protection elements and
- optimal choice of control system for switching elements.

V. CONCLUSION

While developing power converters, one needs to consider the causes of appearance and negative effects of parasitic inductances which can affect the reliability and efficiency of switching elements which are often key parts of the converter. The basic principles of the appearance and limiting of the overvoltage influence on the converter operation were shown in the paper. Special attention was devoted to the intelligent transistor control as an efficient method of overvoltage prevention. An example of application of specially designed control circuit which reduces overvoltage by slowing down the transistor OFF time was demonstrated. The provided results, obtained using a simulation and experimental measurements on the developed converter prototype, show that a combination of active and passive overvoltage protection, together with intelligent control, can provide an efficient overvoltage protection to the *IGBT* transistor.

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